Solving the MDETools Challenge using Embedded Engineer

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MDETools Challenge

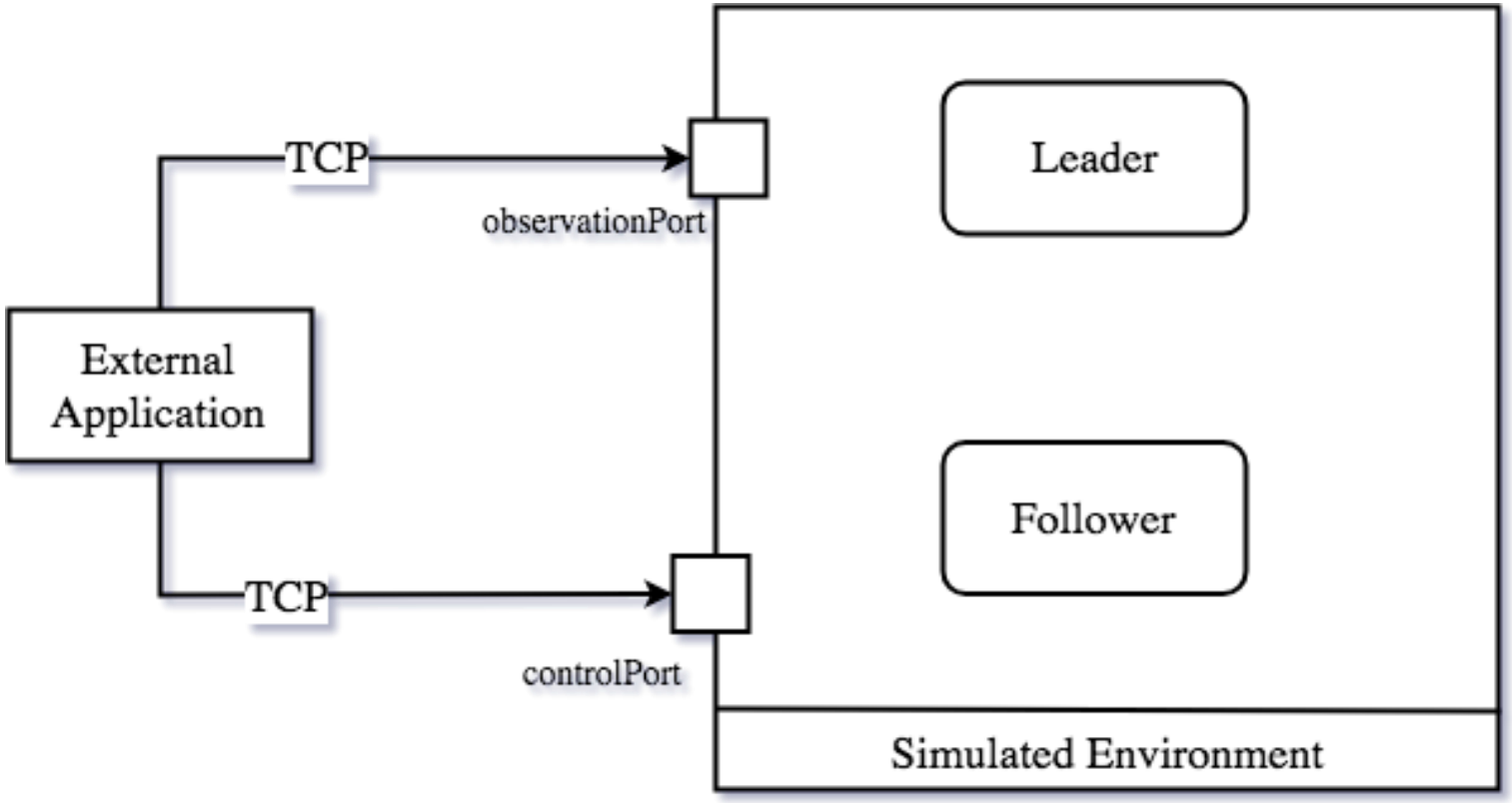

Figure from MDETool Challenge 2018 Website

MDETools Challenge

Control Commands

Message Format	Return Message	Description
"Rover,setForwardPower(<Int>)"	None	Set the power applied to all wheels as a percentage of max power (-100 to 100)
"Rover,incrementPower(<Int>)"	None	Increment the power applied to all wheels as a percentage of max power (-100 to 100)
"Rover,setLRPower(<Int>,<Int>)"	None	Set the power of the left and right wheels as percentages of max power (-100 to 100). First is for left side and the second for right side
"Rover,brake(<Int>)"	None	Apply the amount of brake power to all wheels as a percentage of max brake force (0-100)
"Rover,GPS()"	"Rover,<posx>,<posz>;"	Returns the x and z coordinates of the `follower` as a Real number
"Rover,getCompass()"	"Rover,<Real>;"	Returns the degrees clockwise from North as a Real number

Observation Commands

Message Format	Return Message	Description
"Leader,GPS()"	"Leader,<posx>,<posz>;"	Returns the x and z coordinates of the `leader` as Real numbers
"Leader,Distance()"	"Leader,<dist>;"	Returns the distance between `follower` and `leader` as a Real number
"ready"	"Simulation Started!"	Indicates your program is ready, and begins the simulation

Text taken from MDETool Challenge 2018 Website